

Amendments to the Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application. Please cancel Claims 6-8, amend Claims 9 and 10, and add new Claims 11-20 as follows:

Listing of Claims:

1. (canceled)
2. (canceled)
3. (canceled)
4. (canceled)
5. (canceled)
6. (canceled)
7. (canceled)
8. (canceled)
9. (currently amended): A remote control and feedback system according to Claim 8 11 wherein ~~said the~~ remote station includes a video camera means for monitoring the interaction of ~~said input object~~ the phallic object with ~~said remote user~~ a remote person at the remote station and producing video signals corresponding to ~~said the~~ interaction.
10. (currently amended): A remote control and feedback system according to Claim 9 11 wherein ~~said~~ the local station includes a local video receiver means and where ~~said the~~ remote station includes a video transmission means transmitter for transmitting

the remote video signals to said the local video receiver ~~means~~ for viewing by said a local user at the local station.

11. (new): A remote control and feedback system comprising a local station and a remote station:

the local station comprising:

a first tube containing a pneumatic fluid, the first tube covered at one end by a flexible rubber fitting and at an opposite end by a second fitting;

a second tube in fluid communication with the first tube via a hose, the second tube including a piston driven by a rod, displacement of the rod and piston within the second tube resulting from the pneumatic fluid being displaced into or out of the first tube, the displacement generating an electronic displacement signal communicated to an input CPU;

the remote station comprising:

an output CPU receiving from the input CPU a signal input corresponding to the displacement signal;

a motor activated by the output CPU;

a thrusting tube positioned inside a steadying tube;

a phallic object attached to an end of the thrusting tube, the motor energizing movement of the thrusting tube.

12. (new): A remote control and feedback system according to Claim 11 wherein the first tube further comprises an elongated bag vented to air outside the first tube.

13. (new): A remote control and feedback system according to Claim 11 wherein the piston is contacted by a spring, the spring pressing against the piston so that the pneumatic fluid is always under pressure and so that the piston always returns to a rest position after the system has undergone a perturbation.

14. (new): A remote control and feedback system according to Claim 11 wherein the pneumatic fluid in the second tube is enclosed in a flexible balloon to ensure no fluid leakage past the piston.

15. (new): A remote control and feedback system according to Claim 11 further comprising a wheel having apertures near a perimeter, the wheel being in contact with the rod in such relationship that movement of the rod causes spinning of the wheel.

16. (new): A remote control and feedback system according to Claim 15 further comprising a light emitting device and a light sensing device positioned in a vicinity of the wheel such that light from the emitting device shines through at least one aperture of the wheel and is received by the light sensing device, the received light being converted to output digital data for use by the input CPU and allowing correlation to amounts of pneumatic fluid being displaced from the first tube.

17. (new): A remote control and feedback system according to Claim 11 further comprising a coil spring activated by the motor, the coil spring rotating around a longitudinal axis of a shaft of the motor, the coil spring being at least partially inserted within the thrusting tube.

18. (new): A remote control and feedback system according to Claim 11 wherein the motor at the remote station imparts motion to a coil spring which then energizes downstream the movement of the thrusting tube.

19. (new): A remote control and feedback system according to Claim 11 wherein the thrusting tube protrudes outward from one end of the steadying tube.

20. (new): A remote control and feedback system according to Claim 11 wherein the motor at the remote station imparts rotary motion to an arm which then energizes downstream the movement of the thrusting tube.